

# Pressure Distribution and stresses under granular heaps with the Distinct Element Method



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#### Shapes for granular heaps:





#### Outline of the problem:

- Many "generic" Models for the pressure distribution under granular heaps are possible.
- A-Priori Calculation on the particle level without any macroscopic modeling  $\Rightarrow$  Molecular dynamics simulation



- In experiment, granular cones show a pressure dip, but not granular wedges.
- Is there a dip at all, and why?

#### Simulation results [1,3]: Force network of a heap:

Resulting stresses:







Angle of the stresses:

No evidence for "fixed pricipal axes" proposed in [2]



#### Effect of Heap Histories & Polydispersity [3]:



- Heap by building the heap layer by layer  $\Rightarrow$  no pressure dip
- Monodisperse heaps  $\Rightarrow$  no pressure dip
- Polydisperse heaps  $\Rightarrow$  pressure dip if constructed in wedge sequence, no pressure dip if constructed in layered sequence
- Consistent with experimental results on 3d-cones [6]

#### Difference between cones and wedges:







## Effects of Cohesion [5]:

- Pouring the heap from a point-like source leads to wedgesequence type of heaps as expected
- For strongly cohesive materials layering occurs even for pointlike-source





## Simulation Method [3]:

Integrator: Predictor-Corrector 5th order  $\rightarrow$  large timestep, high stability,  $dt = 0.1 \sqrt{m/Y} \cdot \pi$ Force Laws:

- Contact force:  $F_{c,\perp} = Y \cdot A/l$ . with inverse characteristic length  $\frac{1}{l} = \frac{l_1 + l_2}{l_1 \cdot l_2}$
- Normal Damping force:

$$F_{d,\perp} = \begin{cases} Y \cdot \frac{\mathrm{d}A}{\mathrm{d}t}/l, & \text{for approach} \\ \max\left(Y \cdot \frac{\mathrm{d}A}{\mathrm{d}t}/l, -F_{c,\perp}\right) & \text{for separation} \end{cases}$$

- Tangential force/ friction:

$$F_{d,\parallel}(t) = F_{d,\parallel}(t - \Delta t) + Y_t \cdot v_t \cdot \Delta t + \sqrt{m_{eff,\parallel} \cdot Y_t} v_t$$

#### **References:**

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